

MODELING WITH COPULAS AND VINES IN ESTIMATION OF DISTRIBUTION ALGORITHMS

Marta Soto^{*,1}, Yasser Gonzalez-Fernandez^{*,2}, Alberto Ochoa^{*,3}

^{*} Instituto de Cibernética, Matemática y Física. Calle 15 No. 551 e/ C y D, Vedado. La Habana, Cuba.

ABSTRACT

The aim of this work is studying the use of copulas and vines in numerical optimization with Estimation of Distribution Algorithms (EDAs). Two EDAs built around the multivariate product and normal copulas, and other two based on pair-copula decomposition of vine models are studied. We analyze empirically the effect of both marginal distributions and dependence structure in order to show that both aspects play a crucial role in the success of the optimization process. The results show that the use of copulas and vines opens new opportunities to a more appropriate modeling of search distributions in EDAs.

KEYWORDS: numerical optimization, estimation of distribution algorithms (EDAs), copula, vines

MSC: 90C59

RESUMEN

El objetivo de este trabajo es presentar un estudio acerca del uso de los modelos probabilísticos cópulas y vines en el contexto de la optimización numérica utilizando algoritmos con estimación de distribuciones (EDAs). Se estudian dos EDAs basados en las cópulas multivariadas producto y normal, además de otros dos algoritmos basados en construcciones con cópulas bivariadas representadas mediante vines. Se realiza un análisis empírico del efecto de las distribuciones marginales y la estructura de dependencia de la distribución multivariada, mostrándose que ambos aspectos juegan un rol esencial en el proceso de optimización. Los resultados muestran que el uso de cópulas y vines brinda nuevas alternativas para lograr un modelado más apropiado de las distribuciones de búsqueda en los EDAs.

1. INTRODUCTION

Estimation of Distribution Algorithms (EDAs) [36, 38] are stochastic optimization methods characterized by the explicit use of probabilistic models. EDAs explore the search space by sampling a probability distribution (search distribution) previously built from promising solutions. Most existing continuous EDAs are based on either the multivariate normal distribution or derived models [11, 31]. However, in situations where empirical evidence reveals significant departures from the normality assumption, these EDAs can construct incorrect models of the search space.

A solution comes with the copula function [39], which provides a way to separate the statistical properties of each variable from the dependence structure: first, the marginal distributions are fitted using a rich variety of univariate models available, and then, the dependence between the variables is modeled using a copula. However, the multivariate copula approach has limitations. The number of multivariate copulas is rather limited, and usually these copulas have only one parameter to describe the overall dependence. Thus, this approach is not appropriate when all pairs of variables do not have the same type or strength of dependence. For instance, the t -copula uses a correlation coefficient per each pair of variables, but has only one degree-of-freedom parameter to characterize the tail dependence of all pairs of variables.

^{*,1} mrosa@icimaf.cu, ^{*,2} ygonzalezfernandez@gmail.com, ^{*,3} ochoa@icimaf.cu

An alternative approach to this problem is the pair-copula construction method (PCC) [8, 9, 29], which allows us to built multivariate distributions using only bivariate copulas. PCC models of multivariate distributions are represented in a graphical way as a sequence of nested trees called vines. These graphical models provide a powerful and flexible tool to deal with complex dependences as far as the pair-copulas in the decomposition can be from different families.

In recent years, several copula-based EDAs have been proposed in the literature. The authors have studied the behavior of these algorithms in test functions [14, 19, 44, 51, 55, 50, 23, 24] and real-world problems [52]. Indeed, the use of copulas has been identified as one of the emerging trends in the optimization of real-valued problems using EDAs [28]. In this work, various models based on copula theory are combined in an EDA: two models are built using the multivariate product and normal copulas and other two are based on two PCC models called C-vine and D-vine. We empirically evaluate the performance of these algorithms on a set of test functions and show that vine-based EDAs are better endowed to deal with problems with different dependences between pair of variables.

The paper is organized as follows. Section ?? introduces the notion of copula and describes two EDAs based on the multivariate product and normal copulas, respectively. Section ?? presents the notion and terminology of vines and presents two EDAs based on C-vine and D-vine models, respectively. Section ?? reports and discusses the empirical investigation. For the sake of completeness, we present in Section ?? a short review of representative EDAs based on copulas, before presenting with the conclusions of our study in Section ??.

2. TWO CONTINUOUS EDAS BASED ON MULTIVARIATE COPULAS

We start with some definitions from copula theory [30, 39]. Consider n random variables $\mathbf{X} = (X_1, \dots, X_n)$ with joint cumulative distribution function F and joint density function f . Let $\mathbf{x} = (x_1, \dots, x_n)$ be an observation of \mathbf{X} . A copula C is a multivariate distribution with uniformly distributed marginals $U(0, 1)$ on $[0, 1]$. Sklar's theorem [49] states that every multivariate distribution F with marginals F_1, F_2, \dots, F_n can be written as

$$F(x_1, \dots, x_n) = C(F(x_1), \dots, F(x_n))$$

and

$$C(u_1, \dots, u_n) = F\left(F_1^{(-1)}(u_1), \dots, F_n^{(-1)}(u_n)\right)$$

where $F_i^{(-1)}$ are the inverse distribution functions of the marginals. If F is continuous then $C(u_1, \dots, u_n)$ is unique. The notion of copulas separates the effect of dependence and margins in a joint distribution [32]. The copula C provides all information about the dependence structure of F , independently of the specification of the marginal distributions.

An immediate consequence of Sklar's theorem is that random variables are independent if and only if their underlying copula is the independence or product copula C_I , which is given by

$$C_I(u_1, \dots, u_n) = u_1 \dots u_n. \quad (2.1)$$

The UMDA proposed in [36] assumes a model of independence of normal margins. Therefore, an EDA based on the product copula is a generalization of the UMDA, which also supports other types of marginal distributions.

Besides UMDA, in [36] the authors also proposed an EDA based on the multivariate normal distribution called Estimation of Multivariate Normal Algorithm (EMNA). It turns out that, indeed EMNA can be also reformulated in copula terms: a normal copula plus normal margins. The Gaussian Copula Estimation of Distribution Algorithm (GCEDA) proposed in [51, 3] uses the multivariate normal (or Gaussian) copula, which is given by

$$C_N(u_1, \dots, u_n; R) = \Phi_R\left(\Phi^{-1}(u_1), \dots, \Phi^{-1}(u_n)\right), \quad (2.2)$$

where Φ_R is the standard multivariate normal distribution with correlation matrix R , and Φ^{-1} denotes the inverse of the standard univariate normal distribution. This copula allows the construction of multivariate distributions with non-normal margins. If this is the case, the joint density is no longer the multivariate normal, though the normal dependence structure is preserved. Therefore, with normal margins, GCEDA is equal to EMNA, otherwise they are different. If the marginal distributions are non-normal, the correlation matrix is estimated using the inversion of the non-parametric estimator Kendall's tau $\hat{R}_{ij} = \sin(\pi/2\hat{\tau}_{ij})$ for each pair of variables $i, j = 1, \dots, n$ [39]. If the resulting matrix \hat{R} is not positive-definite, the correction proposed in [43] can be applied.

In this work, all margins used by the algorithms are always of the same type, either normal (Gaussian) or empirical smoothed with a normal kernel. In particular, the estimation of the normal margin $\hat{F}_i \sim \mathcal{N}(x_i; \hat{\mu}_i, \hat{\sigma}_i^2)$ requires the computation of the mean $\hat{\mu}_i$ and variance $\hat{\sigma}_i^2$ from the selected population. The empirical margin is estimated using the normal kernel estimator given by

$$\hat{F}_i(t) = \frac{1}{N} \sum_{j=1}^N \Phi\left(\frac{t - y_j}{h}\right),$$

where the set $\{y_1, \dots, y_N\}$ is the sample of the i^{th} variable of \mathbf{X} in the selected population with N individuals. The bandwidth parameter h is computed according to the rule-of-thumb of [48]. In this paper, the subscripts g and e in the name of the algorithms denote the use of Gaussian and empirical margins, respectively (e.g., UMDA_g and GCEDA_e).

The generation of a new individual in GCEDA_g and GCEDA_e starts with the simulation of a vector (u_1, \dots, u_n) from the multivariate normal copula [18]. In GCEDA_g, the inverse distribution function $x_i = \hat{F}_i^{-1}(u_i; \hat{\mu}_i, \hat{\sigma}_i^2)$ is used to obtain each x_i of the new individual. In GCEDA_e, x_i is found by solving the inverse of the marginal cumulative distribution using the Newton-Raphson method [4].

3. EDAS BASED ON VINES

This section provides a brief description of the C-vine and D-vine models and the motivation for using them to construct the search distributions in EDAs. We also present CVEDA and DVEDA, our third and fourth algorithms.

3.1. From Multivariate Copulas to Vines

The multivariate copula approach has several limitations. Most of the available parametric copulas are bivariate and the multivariate extensions usually describe the overall dependence by means of only one parameter. This approach is not appropriate when there are pairs of variables with different type or strength of dependence. The pair-copula construction method (PCC) is an alternative approach to this problem. PCC method was originally proposed in [29] and this result was later developed in [8, 9, 29]. The decomposition of a multivariate distribution in pair-copulas is a general and flexible method for constructing multivariate distributions. In PCC models, bivariate copulas are used as building blocks. The graphical representation of these constructions involves a sequence of nested trees, called regular vines. Pair-copula constructions of regular vines allows to model a rich variety of types of dependences as far as the bivariate copulas can belong to different families.

3.2. Pair-Copula Constructions of C-vines and D-vines

Vines are probabilistic dependence models that allow us to decompose a multivariate distribution function $f(x_1, \dots, x_n)$ into bivariate copulas and marginal densities. A vine on n variables is a nested set of trees T_1, \dots, T_{n-1} , where the edges of tree j are the nodes of the tree $j+1$ with $j = 1, \dots, n-2$. Regular vines constitute a special case of vines in which two edges in tree j are joined by an edge in tree $j+1$ only if these edges share a common node. Two instances of regular vines are the canonical (C) and drawable (D) vines. In Figure 1, a graphical representation of a C-vine

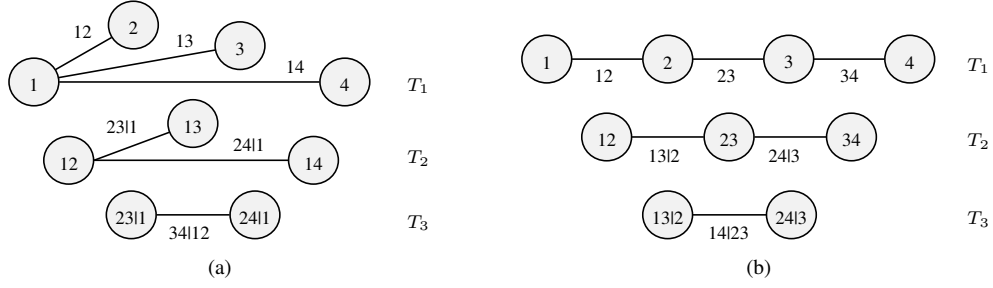


Figure 1: Four-dimensional C-vine (a) and D-vine (b). In a C-vine, each tree T_j has a unique node with $n - j$ edges. The node with $n - 1$ edges in tree is called the root. In a D-vine, no node is connected to more than two edges.

and D-vine for four dimensions is given. Each graphical model gives a specific way of decomposing the density. In particular, for a C-vine, $f(x_1, \dots, x_n)$ is given by

$$\prod_{k=1}^n f(x_k) \prod_{j=1}^{n-1} \prod_{i=1}^{n-j} c_{j,j+i|i,\dots,j-1}(F(x_j|x_1, \dots, x_{j-1}), F(x_{j+i}|x_1, \dots, x_{j-1})), \quad (3.3)$$

and for a D-vine, the density is equal to

$$\prod_{k=1}^n f(x_k) \prod_{j=1}^{n-1} \prod_{i=1}^{n-j} c_{i,i+j|i+1,\dots,i+j-1}(F(x_i|x_{i+1}, \dots, x_{i+j-1}), F(x_{i+j}|x_{i+1}, \dots, x_{i+j-1})), \quad (3.4)$$

where j identifies the trees and i denotes the edges in each tree.

Note that in (3.3) and (3.4) the joint density consists of marginal densities $f(x_k)$ and pair-copula densities evaluated at conditional distribution functions of the form $F(x | \mathbf{v})$. In [29] it is showed that conditional distribution of pair-copulas constructions are given by

$$F(x | \mathbf{v}) = \frac{\partial C_{xv_j|\mathbf{v}_{-j}}(F(x | \mathbf{v}_{-j}), F(v_j | \mathbf{v}_{-j}))}{\partial F(v_j | \mathbf{v}_{-j})}, \quad (3.5)$$

where $C_{xv_j|\mathbf{v}_{-j}}$ is a bivariate copula distribution function, \mathbf{v} is a n -dimensional vector, v_j is the j components of \mathbf{v} and \mathbf{v}_{-j} denotes the remaining component. The recursive evaluation of $F(x | \mathbf{v})$ yields the expression

$$F(x | v) = \frac{\partial C_{xv}(F_x(x), F_v(v))}{\partial F_v(v)}.$$

For the special case (unconditional) when v is univariate, and x and v are standard uniform, $F(x | v)$ reduces to

$$F(x | v) = \frac{\partial C_{xv}(x, v, \Theta)}{\partial v}.$$

where Θ is the set of parameters for the bivariate copula of the joint distribution function of x and v . To facilitate de computation of $F(x | v)$, the function

$$h(x, v; \theta) = F(x | v) = \frac{\partial C_{xv}(x, v; \Theta)}{\partial v}, \quad (3.6)$$

is defined. The inverse of h with respect to the first variable h^{-1} is also defined. The expressions of these functions of the bivariate copulas used in this work are given in Appendix ??.

3.3. Vine Estimation of Distribution Algorithms

Vine Estimation of Distribution Algorithms (VEDAs) [23, 50] are a class of EDAs that uses vines to model the search distributions. CVEDA and DVEDA are VEDAs based on C-vines and D-vines, respectively. Now we describe the particularities of the estimation and simulation steps of these algorithms.

3.3.1. Estimation

The estimation procedures of C-vines and D-vines proposed and developed in [1] consist of the following main steps: selection of a specific factorization, choice of the pair-copula types in the factorization, and estimation of the copula parameters. Next we describe these steps according to our implementation.

1. Selection of a specific factorization:

The selection of a specific pair-copula decomposition implies to choose an appropriate order of the variables, which can be obtained by several ways: given as parameter, selected at random, chosen by greedy heuristics. We use greedy heuristics for detecting the most important bivariate dependences.

Assumed a specific factorization, the first step of the estimation procedure consist in assigning weights to the edges. As weights we use the absolute value of the empirical Kendall's tau between pair of variables [39]. The next step consist in determining the appropriate order of the variables of the decomposition, which depends on the type of pair-copula decomposition:

- In a C-vine, the tree that maximizes the sum of the weights of one node (the root node) to the others is chosen by the greedy heuristic as the appropriate factorization.
- In a D-vine, the first tree is selected by maximizing the weighted sequence of the original variables. Since the first tree of the vine is a chain of variables, this problem can be transformed into a traveling salesman problem (TSP) instance where one must find a cycle that visits all the cities (i.e. variables) starting from an initial dummy node with zero weight on all edges to the other nodes – see [12] for the details of this transformation. For efficiency reasons, we use the cheapest insertion heuristic, an approximate solution of TSP presented in [42]. In a D-vine, the structure of remaining trees is completely determined by the structure of the first tree.

A pair-copula decomposition has $n - 1$ trees and requires to fit $n(n-1)/2$ copulas. Assuming conditional independence might simplify the estimation step, since if X and Y are conditionally independent given \mathbf{V} , then $c_{xy|\mathbf{v}}(F_{x|\mathbf{v}}(x | \mathbf{v}), F_{y|\mathbf{v}}(y | \mathbf{v})) = 1$. This property is used by a model selection procedure proposed in [12], which consists in truncating the pair-copula decomposition at specific tree level, fitting the product copula in the subsequent trees. For detecting the truncation tree level, this procedure uses either the Akaike Information Criterion (AIC) [2] or the Bayesian Information Criterion (BIC) [47], such that the tree T_{j+1} is expanded if the value of the information criteria calculated up to the tree T_{j+1} is smaller than the value obtained up to the previous tree. Otherwise, the vine is truncated at tree level T_j .

2. Choice of the pair-copula types in the factorization and estimation of the copula parameters.

- (a) Determine the pair-copula types to use in tree 1 using the original data by applying a goodness of fit test.
- (b) Compute observations – i.e. conditional distribution functions – using the copula parameters from tree 1 and the $h(\cdot)$ function.
- (c) Determine the pair-copula types in tree 2 in the same way as in tree 1, using the observations from (b).
- (d) Repeat (b) and (c) for the following trees.

Selection of pair-copulas is accomplished in different ways [22]. In this work, the Cramér-von Mises statistics

$$S_N = \sum_{i=1}^N (C_E(u_i, v_i) - C_{\Theta}(u_i, v_i))^2 \quad (3.7)$$

is minimized. N is the sample size, Θ is the set of parameters of a bivariate copula C_{Θ} , and C_E is the empirical copula. We first test the product copula [21]. If there is enough evidence against the null hypothesis of independence (at a fixed significance level of 0.1) it is rejected. If this is the case, the copula C_{Θ} that minimizes S_N is chosen.

We combine different types of bivariate copulas: normal, Student's t , Clayton, rotated Clayton, Gumbel and rotated Gumbel. The normal copula is neither lower nor upper tail dependent while the Student's t copula is both lower and upper tail dependent. The Clayton and rotated Clayton copulas are lower tail dependent while the Gumbel and rotated Gumbel copulas are upper tail dependent.

The parameters of all these copulas, but the Student's t , are estimated using the inversion of Kendall's tau [20]. The correlation coefficient for the Student's and normal copulas are computed similarly. The degrees of freedom of the Student's t copula are estimated by maximum likelihood with the correlation parameter held fixed [15]. We consider an upper bound of 30 for the degrees of freedom because for this value the bivariate Student's t copula becomes almost indistinguishable from the bivariate normal copula [17].

3.3.2. Simulation

Simulation from vines [7, 8, 33] is based on the conditional distribution method described in [16]. The general algorithm for sampling n dependent uniform $[0, 1]$ variables is common for C-vines and D-vines. First, sample n independent uniform random numbers $w_i \in (0, 1)$ and then compute

$$\begin{aligned} x_1 &= w_1 \\ x_2 &= F_{2|1}^{-1}(w_2|x_1) \\ x_3 &= F_{3|1,2}^{-1}(w_3|x_1, x_2) \\ &\vdots \\ x_n &= F_{n|1,2,\dots,n-1}^{-1}(w_n|x_1, \dots, x_{n-1}). \end{aligned}$$

To determine $F(x_j | x_1, x_2, \dots, x_{j-1})$ for each j , the expressions (3.5) and (3.6) are used for both structures, although the choice of the v_j in (3.5) is different (see (3.3) and (3.4)). For details about the sampling algorithms, see [1].

4. EMPIRICAL INVESTIGATION

This section outlines the experimental setup and presents the numerical results. The experiments aim to show that both the marginal distributions and the dependence structure are crucial for the optimization using EDAs. For the empirical study we use the statistical environment R [41] and the tools provided by the packages `copulaedas` [25, 27] and `vines` [26].

4.1. Experimental Design

The well known Sphere, Griewank, Ackley and Summation Cancellation test functions [10] are considered as benchmark problems in $n = 10$ dimensions. The definition of these functions for $\mathbf{x} = (x_1, \dots, x_n)$ is given below:

$$f_{\text{Sphere}}(\mathbf{x}) = \sum_{i=1}^n x_i^2$$

$$f_{\text{Griewank}}(\mathbf{x}) = 1 + \sum_{i=1}^n \frac{x_i^2}{4000} - \prod_{i=1}^n \cos\left(\frac{x_i}{\sqrt{i}}\right)$$

$$f_{\text{Ackley}}(\mathbf{x}) = -20 \exp\left(-0.2 \sqrt{\frac{1}{n} \sum_{i=1}^n x_i^2}\right) - \exp\left(\frac{1}{n} \sum_{i=1}^n \cos(2\pi x_i)\right) + 20 + \exp(1)$$

$$f_{\text{Summation Cancellation}}(\mathbf{x}) = \frac{1}{10^{-5} + \sum_{i=1}^n |y_i|}, \quad y_1 = x_1, \quad y_i = y_{i-1} + x_i$$

Sphere, Griewank and Ackley are minimization problems that have global optimum at $\mathbf{x} = (0, \dots, 0)$ with evaluation zero. Summation Cancellation is a maximization problem that has global optimum at $\mathbf{x} = (0, \dots, 0)$ with evaluation 10^5 .

To ensure a fair comparison between the algorithms, we find the minimum population size required by each algorithm to reach the global optimum of the function in 30 of 30 independent trials. This critical population size is determined using a bisection method [40]. The algorithm stops when either the global optimum is found with a precision of 10^{-6} or after 500,000 function evaluations. A truncation selection of 0.3 is used [37] and no elitism.

In the initial population, each variable is sampled uniformly in a given real interval. We say an interval is symmetric if the value that X_i takes in the global optimum of the function is located in the middle of the given interval. Otherwise, we call it asymmetric. The symmetric intervals used in the experiments are: $[-600, 600]$ in Sphere and Griewank, $[-30, 30]$ in Ackley, and $[-0.16, 0.16]$ in Summation Cancellation. The asymmetric intervals are: $[-300, 900]$ in Sphere and Griewank, $[-15, 45]$ in Ackley, and $[-0.08, 0.24]$ in Summation Cancellation.

4.2. Effect of the Marginal Distributions

In this section we investigate the effect of the marginal distributions under two assumptions: independence and joint normal dependence. The results obtained with UMDA and GCEDA in symmetric and asymmetric intervals are given in Tables 1–4. We summarize the results in the following four points.

Table 1: Results of UMDA and GCEDA in Sphere.

Algorithm	Success	Population	Evaluations	Best Evaluation
$X_i \in [-600, 600], i = 1, \dots, 10$				
UMDA _g	30/30	86	3,996.1±89.5	6.9E-07 ± 1.9E-07
UMDA _e	30/30	82	5,466.6 ± 164.4	7.0E-07 ± 1.7E-07
GCEDA _g	30/30	325	13,769.1±248.5	6.6E-07 ± 1.6E-07
GCEDA _e	30/30	259	14,581.7 ± 403.2	7.1E-07 ± 2.0E-07
$X_i \in [-300, 900], i = 1, \dots, 10$				
UMDA _g	30/30	118	5,502.7±125.8	6.4E-07 ± 1.9E-07
UMDA _e	30/30	83	5,513.9 ± 180.6	7.4E-07 ± 1.9E-07
GCEDA _g	24/30	2000	171,666.6 ± 166,976.4	3.0E+01 ± 8.4E+01
GCEDA _e	30/30	522	29,023.2±541.4	7.2E-07 ± 2.3E-07

Table 2: Results of UMDA and GCEDA in Griewank.

Algorithm	Success	Population	Evaluations	Best Evaluation
$X_i \in [-600, 600], i = 1, \dots, 10$				
UMDA _g	30/30	113	5,179.1±210.0	7.2E-07 ± 1.7E-07
UMDA _e	30/30	475	27,961.6 ± 1,387.5	7.0E-07 ± 1.8E-07
GCEDA _g	30/30	304	12,798.4±351.1	6.6E-07 ± 1.7E-07
GCEDA _e	30/30	324	17,895.6 ± 536.0	6.7E-07 ± 1.7E-07
$X_i \in [-300, 900], i = 1, \dots, 10$				
UMDA _g	30/30	110	5,261.6±284.6	6.7E-07 ± 2.1E-07
UMDA _e	30/30	449	26,580.8 ± 1,003.3	7.3E-07 ± 1.7E-07
GCEDA _g	22/30	2000	201,333.3 ± 183,220.5	1.3E-01 ± 2.5E-01
GCEDA _e	30/30	588	32,438.0±860.9	8.0E-07 ± 1.5E-07

1. As the asymmetry of the interval grows the performance of all the algorithms deteriorate. This effect is larger with normal margins.

We illustrate this point through the analysis of the UMDA behavior. With symmetric intervals, UMDA_g outperforms UMDA_e, which is particularly notable in the Griewank function. As example, Figure 2 illustrates that the variance of the normal margin shrinks faster than the variance of the normal kernel margin. The larger variance of the empirical margin can be explained by the existence of global and local optima, all of which are captured by the normal kernel margins. Figure 3-(left) shows several peaks located near the values that the variable takes in the global and local optima, while in Figure 3-(right) the peak of the normal density lies in the middle of the interval regardless of the shape of the data. For this same reason, with symmetric interval, the algorithms behave better with normal margins than with empirical.

2. With asymmetric intervals, GCEDA with normal kernel margins is much better than with normal margins.

With symmetric intervals, UMDA and GCEDA with normal margins behave better than with normal kernel margins. However, if the initial population is sampled asymmetrically, this situation changes, which is more remarkable in GCEDA (even GCEDA_g might not converge). This situation is illustrated in the optimization

Table 3: Results of UMDA and GCEDA in Ackley.

Algorithm	Success	Population	Evaluations	Best Evaluation
$X_i \in [-30, 30], i = 1, \dots, 10$				
UMDA _g	30/30	88	5,426.6±127.2	8.2E − 07 ± 1.0E − 07
UMDA _e	30/30	94	8,024.4 ± 210.1	8.6E − 07 ± 8.4E − 08
GCEDA _g	30/30	325	18,178.3±207.8	8.0E − 07 ± 1.5E − 07
GCEDA _e	30/30	303	21,866.5 ± 338.3	8.1E − 07 ± 1.4E − 07
$X_i \in [-15, 45], i = 1, \dots, 10$				
UMDA _g	30/30	95	5,959.6±111.3	7.7E − 07 ± 1.1E − 07
UMDA _e	30/30	91	7,995.8 ± 183.1	8.3E − 07 ± 1.1E − 07
GCEDA _g	30/30	782	45,460.2 ± 532.8	8.0E − 07 ± 1.2E − 07
GCEDA _e	30/30	357	26,013.4±493.7	8.5E − 07 ± 8.2E − 08

Table 4: Results of UMDA and GCEDA in Summation Cancellation.

Algorithm	Success	Population	Evaluations	Best Evaluation
$X_i \in [-0, 16, 0, 16], i = 1, \dots, 10$				
UMDA _g	0/30	2000	500,000.0 ± 0,0	6.9E + 02 ± 5.0E + 02
UMDA _e	0/30	2000	500,000.0 ± 0,0	1.0E + 03 ± 1.2E + 03
GCEDA _g	30/30	325	38,848.3±327,6	1.0E + 05 ± 1.2E − 07
GCEDA _e	30/30	1525	213,144.1 ± 1,907.3	1.0E + 05 ± 1.0E − 07
$X_i \in [-0, 08, 0, 24], i = 1, \dots, 10$				
UMDA _g	0/30	2000	500,000.0 ± 0.0	5.6E + 02 ± 3.8E + 02
UMDA _e	0/30	2000	500,000.0 ± 0.0	1.9E + 03 ± 1.9E + 03
GCEDA _g	4/30	2000	467,000.0 ± 85,577.5	1.3E + 04 ± 3.4E + 04
GCEDA _e	30/30	1525	215,330.0±1,621.8	1.0E + 05 ± 1.1E − 07

of the Griewank function with GCEDA_g and GCEDA_e. Figure 4 shows both the normal and normal kernel densities of the first variable, which are estimated at generations 10, 15, 20, 25 and 30. We recall that the zero value corresponds to the value of the variable in the global optimum. In Figure 4-(top), note that with normal margins the zero is located at the tail of the normal density, thus, it is sampled with low probability. As the evolution proceeds, the density moves away from zero. In Figure 4-(bottom), the normal kernel margins capture more local features of the distribution and it is more likely that good points are sampled.

3. In problems where UMDA exhibits good performance, the introduction of correlations by GCEDA seems to be harmful.

Sphere, Griewank and Ackley can be easily optimized by UMDA as far as the marginal information is enough for finding the global optimum. GCEDA requires to compute many parameters and larger populations are needed to estimate them reliably. Figure 5 illustrates this issue in the Sphere function. We run UMDA_g with its critical population. For GCEDA_g we use different population sizes, including the critical population of these two algorithms (86 and 325, respectively). The box-plot shows that GCEDA_g achieves the means and variances of UMDA_g but uses larger populations.

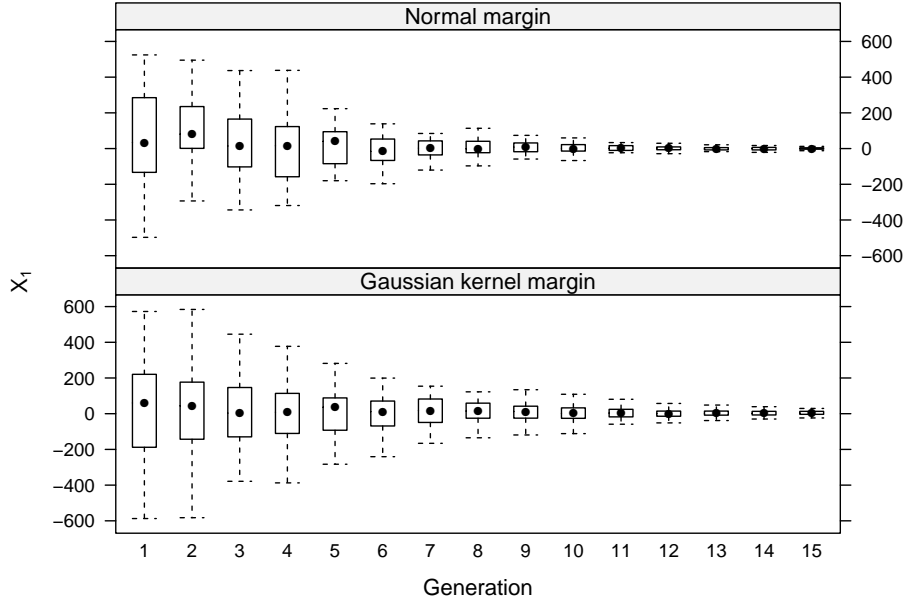


Figure 2: Box-plots illustrating the evolution of the first variable of Griewank in the selected population of $UMDA_g$ (top) and $UMDA_e$ (bottom) for 15 generations.

4. UMDA is not capable of optimizing Summation Cancellation.

Summation Cancellation has multivariate linear interactions between the variables [11]. As far as this information is essential for finding the global optimum, UMDA fails to optimize this function with both normal and kernel margins, while GCEDA is successful, though this algorithm is also sensitive to the effect of asymmetry.

Summarizing, we can say that both aspects – the statistical properties of the marginal distributions and the dependence structure – play a crucial role for the success of EDA optimization. In the following sections we deal with the latter aspect in more detail.

4.3. Effect of the Dependence Structure

This section reports the most important results of our work. We investigate the effect of combining different copulas, applying the truncation strategy, and selecting the structure of C-vines and D-vines in the performance of VEDA.

4.3.1. Combining Different Bivariate Copulas

In this section we assess the effect of using different types of dependences when all the marginal distributions are normal. The experimental results obtained with CVEDA and DVEDA in Sphere, Griewank, Ackley and Summation Cancellation are presented in Tables 5–8, respectively. The studied algorithms are $CVEDA_{9, greedy, g}$ and $DVEDA_{9, greedy, g}$. The sub-indexes mean that they perform a complete construction of the vines (9 trees), use greedy heuristics to represent the stronger dependences in the first tree, and all margins are normal.

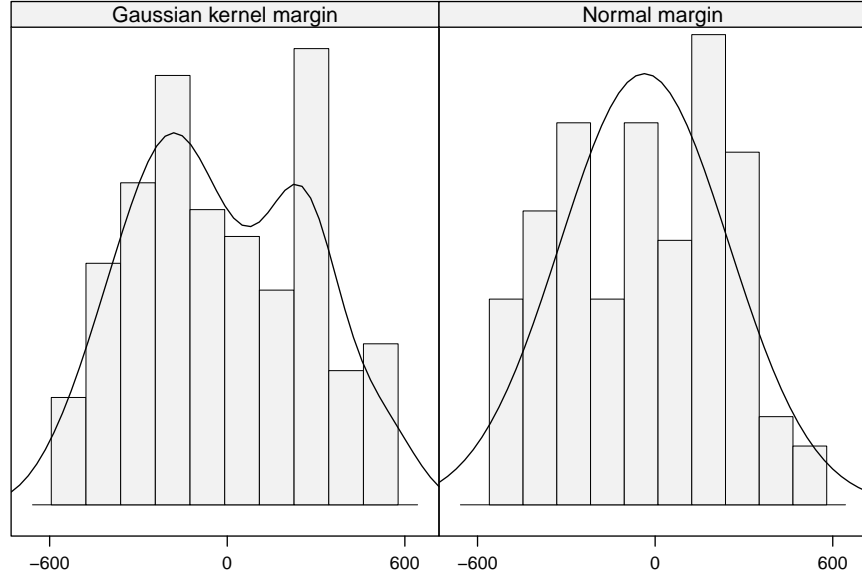


Figure 3: Histograms of the first variable of the Griewank function in the selected population of the second generation with UMDA_e (left) and UMDA_g (right). The empirical and normal densities are superposed, respectively.

Table 5: Results of VEDA in Sphere with $X_i \in [-600, 600]$, $i = 1, \dots, 10$.

Algorithm	Success	Population	Evaluations	Best Evaluation
CVEDA _{9, greedy, g}	30/30	188	$8,033.8 \pm 170.5$	$6.8E - 07 \pm 2.1E - 07$
DVEDA _{9, greedy, g}	30/30	207	$8,818.2 \pm 192.9$	$7.0E - 07 \pm 1.8E - 07$

In the investigated problems the following hold:

1. CVEDA and DVEDA exhibit a good performance in problems with both strong and weak dependences between the variables.

While UMDA uses the independence model and GCEDA assumes a linear dependence structure, CVEDA and DVEDA do not assume the same type of dependence across all pairs of variables. The estimation procedures used by the vine-based algorithms select among a group of candidate bivariate copulas, the one that fits the data appropriately. CVEDA and DVEDA perform, in general, between UMDA and GCEDA in terms of the number of function evaluations.

2. CVEDA exhibits better results than DVEDA in easy problems for UMDA (Sphere, Griewank and Ackley).

The model used by DVEDA allows a more freely selection of the bivariate dependences that will be explicitly modeled, while the model used by CVEDA has a more restrictive structure. These characteristics enable DVEDA to fit in the first tree a greater number of bivariate copulas that represent dependences. This may explain why DVEDA requires larger sample sizes than CVEDA, and thus more function evaluations.

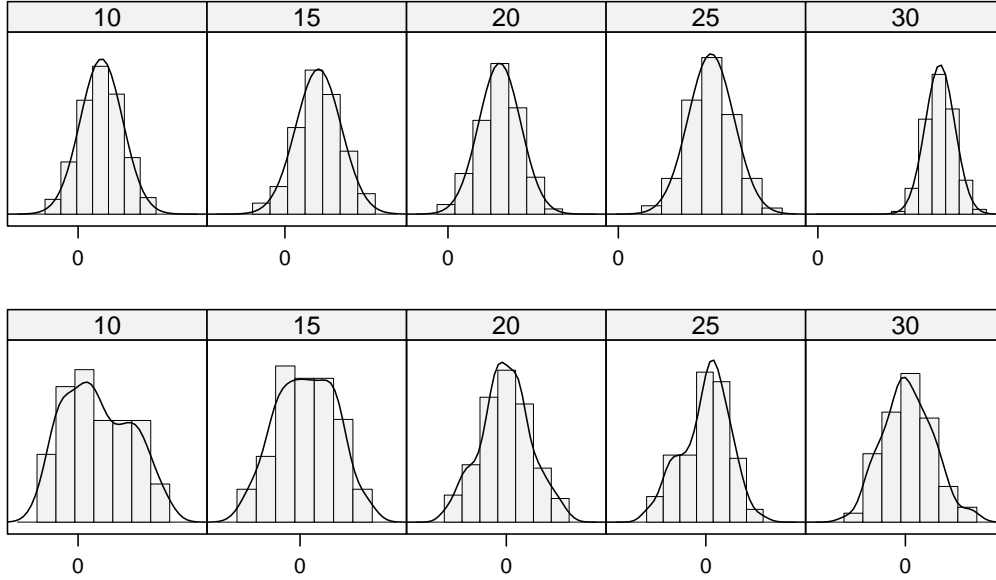


Figure 4: Marginal distributions of the first variable of Griewank with GCEDA_g (top) and GCEDA_e (bottom) in the generations 10, 15, 20, 25 and 30.

Table 6: Results of VEDA in Griewank with $X_i \in [-600, 600]$, $i = 1, \dots, 10$.

Algorithm	Success	Population	Evaluations	Best Evaluation
$\text{CVEDA}_{9, \text{greedy}, g}$	30/30	213	$9, 151.9 \pm 452.6$	$6.5\text{E} - 07 \pm 1.8\text{E} - 07$
$\text{DVEDA}_{9, \text{greedy}, g}$	30/30	225	$9, 630.0 \pm 309.2$	$6.9\text{E} - 07 \pm 1.5\text{E} - 07$

3. CVEDA has much better results than DVEDA in Summation Cancellation.

Summation Cancellation reaches its global optimum when the sum in the denominator of the fraction is zero. The i -th term of this sum is the sum of the first i variables of the function. Thus, the first variables have a greater influence in the value of the sum. The selected populations reflect these characteristics including stronger associations between the first variables and the next ones. A C-vine structure provides a more appropriate modeling of this situation than a D-vine structure, since it is possible to find a variable that governs the interactions in the sample. However, as it was pointed out before, here the interesting issue is the success of GCEDA. The explanation is simple. On one hand, Summation Cancellation has multivariate linear interactions between the variables [11]. On the other hand, the multivariate normal distribution is indeed, a linear model of interactions.

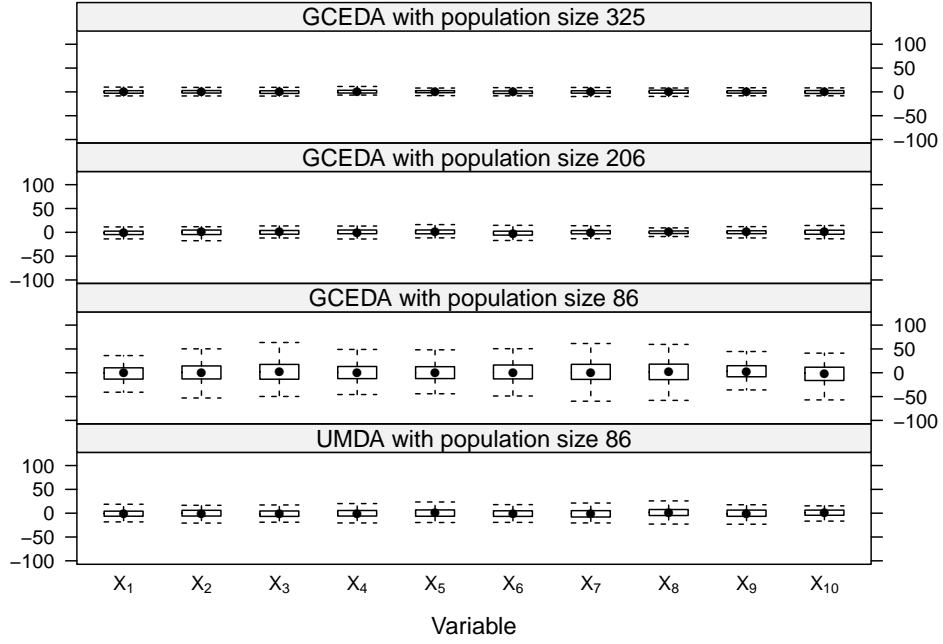


Figure 5: Mean and variance of each variable in the selected population at 10^{th} generation with $GCEDA_g$ and $UMDA_g$ in Sphere. $GCEDA_g$ requires larger populations than $UMDA_g$.

4. Combining normal and non-normal copulas worsens the results of the vine-based algorithms in Summation Cancellation.

Since the multivariate linear interactions of Summation Cancellation are readily modeled with a multivariate normal dependence structure, $GCEDA$ has better performance than vine-based EDAs, which can fit copulas of different families (Tables 4 and 8). We repeated the experiments using only product and normal copulas. The results show similar performance of $CVEDA_{N, 9, greedy, g}$, $DVEDA_{N, 9, greedy, g}$ and $GCEDA$, being $CVEDA$ slightly better than $DVEDA$.

Regarding the results presented in this section, we can summarize that EDAs using pair-copula constructions exhibit a more robust behavior than EDAs using multivariate product or normal copula in the given set of benchmark functions.

4.3.2. Truncation of C-vines and D-vines

In order to reduce the number of levels of the pair-copula decompositions – and hence simplify the models – we apply two different approaches: the truncation level is given as a parameter or it is determined by a model selection procedure based on AIC or BIC (see Section 3.3.1.). We study the effect of both strategies in the Sphere and Summation Cancellation functions, as examples of problems with weak and strong correlated variables. The following algorithms are compared:

Table 7: Results of VEDA in Ackley with $X_i \in [-30, 30]$, $i = 1, \dots, 10$.

Algorithm	Success	Population	Evaluations	Best Evaluation
CVEDA _{9, greedy, g}	30/30	213	$11,984.8 \pm 184.9$	$7.9E - 07 \pm 1.5E - 07$
DVEDA _{9, greedy, g}	30/30	213	$11,920.9 \pm 197.6$	$7.9E - 07 \pm 1.3E - 07$

Table 8: Results of VEDA in Summation Cancellation with $X_i \in [-0, 16, 0, 16]$, $i = 1, \dots, 10$.

Algorithm	Success	Population	Evaluations	Best Evaluation
CVEDA _{9, greedy, g}	30/30	625	$84,958.3 \pm 786.0$	$1.0E + 05 \pm 1.1E - 07$
CVEDAN _{9, greedy, g}	30/30	319	$43,373.3 \pm 539.5$	$1.0E + 05 \pm 1.3E - 07$
DVEDA _{9, greedy, g}	30/30	1400	$161,840.0 \pm 1,352.5$	$1.0E + 05 \pm 9.3E - 08$
DVEDAN _{9, greedy, g}	30/30	488	$58,494.9 \pm 457.3$	$1.0E + 05 \pm 1.3E - 07$

- CVEDA_{3, greedy, g} and DVEDA_{3, greedy, g} truncate the vines at the third tree.
- CVEDA_{6, greedy, g} and DVEDA_{6, greedy, g} truncate the vines at the sixth tree.
- CVEDA_{AIC, greedy, g} and DVEDA_{AIC, greedy, g} determine the required number of trees using AIC.
- CVEDA_{BIC, greedy, g} and DVEDA_{BIC, greedy, g} determine the required number of trees using BIC.

The results of the experiments in Sphere and Summation Cancellation are presented in Tables 9 and 10, respectively. The main results are summarized in the following points:

1. The algorithms that use the truncation strategy based on AIC or BIC exhibit a more robust behavior.

The necessary number of trees depends on the characteristics of the function being optimized. In the Sphere function, a small number of trees is quite enough, while in Summation Cancellation it is preferable to expand the pair-copula decomposition completely. In both functions the better results are obtained when the truncation level is determined by a model selection procedure based on AIC or BIC, since cutting the model arbitrarily could cause that important dependences are not represented. The latter was the strategy applied in [45], where a D-vine with normal copulas was only expanded up to the second tree. A combination of both strategies could be an appropriate solution.

2. For VEDA the truncation method based on AIC is preferable than the truncation based on BIC.

In the Sphere function, the vine-based EDAs that use truncation based on BIC perform better than those based on AIC. The opposite occurs in Summation Cancellation, where DVEDA_{BIC, greedy, g} fail in the 30 runs. Both situations are caused by the term that penalizes the number of parameters in these metrics. BIC prefers models with less number of copulas than AIC [12], which is good for Sphere, but compromises the convergence of the algorithms in Summation Cancellation. The algorithms using AIC have a good performance in both functions. Specifically, in Sphere the number of trees was never greater than three with CVEDA and four with DVEDA; in Summation Cancellation both algorithms perform complete construction of the vines (nine trees).

In the following section, we study the importance of the selection of the bivariate dependences explicitly modeled in the first tree of C-vines and D-vines.

Table 9: Results of VEDA with truncation in Sphere with $X_i \in [-600, 600]$, $i = 1, \dots, 10$.

Algorithm	Success	Population	Evaluations	Best Evaluation
CVEDA ₃ , greedy, g	30/30	175	7,536.6 \pm 151.9	6.5E - 07 \pm 2.2E - 07
CVEDA ₆ , greedy, g	30/30	191	8,174.8 \pm 176.6	6.7E - 07 \pm 1.9E - 07
CVEDA _{AIC} , greedy, g	30/30	163	7,106.8 \pm 139.3	6.6E - 07 \pm 2.0E - 07
CVEDA _{BIC} , greedy, g	30/30	113	5,017.2 \pm 134.6	6.8E - 07 \pm 1.6E - 07
DVEDA ₃ , greedy, g	30/30	191	8,149.3 \pm 161.2	6.5E - 07 \pm 1.8E - 07
DVEDA ₆ , greedy, g	30/30	207	8,818.2 \pm 128.6	6.9E - 07 \pm 1.8E - 07
DVEDA _{AIC} , greedy, g	30/30	163	6,992.7 \pm 144.2	6.5E - 07 \pm 1.9E - 07
DVEDA _{BIC} , greedy, g	30/30	138	6,026.0 \pm 127.2	7.0E - 07 \pm 2.2E - 07

Table 10: Results of VEDA with truncation in Summation Cancellation with $X_i \in [-0, 16, 0, 16]$, $i = 1, \dots, 10$.

Algorithm	Success	Population	Evaluations	Best Evaluation
CVEDA ₃ , greedy, g	0/30	2000	500,000.0 \pm 0.0	2.6E + 03 \pm 3.4E + 03
CVEDA ₆ , greedy, g	0/30	2000	500,000.0 \pm 0.0	3.7E + 04 \pm 3.2E + 04
CVEDA _{AIC} , greedy, g	30/30	650	90,003.3 \pm 1,262.8	1.0E + 05 \pm 1.2E - 07
CVEDA _{BIC} , greedy, g	30/30	800	108,506.6 \pm 1,647.3	1.0E + 05 \pm 9.8E - 08
DVEDA ₃ , greedy, g	0/30	2000	500,000.0 \pm 0.0	8.4E + 04 \pm 2.5E + 04
DVEDA ₆ , greedy, g	10/30	2000	412,133.3 \pm 12,8711.1	9.9E + 04 \pm 1.7E + 02
DVEDA _{AIC} , greedy, g	30/30	1300	152,750.0 \pm 1,404.1	1.0E + 05 \pm 1.0E - 07
DVEDA _{BIC} , greedy, g	26/30	2000	285,000.0 \pm 100,221.0	9.9E + 04 \pm 6.9E - 03

4.3.3. Selection of the Structure of C-vines and D-vines

The aim of this section is to assess the importance of selecting an appropriate ordering of the variables in the pair-copula decomposition for the optimization with vine-based EDAs.

Here we repeat the experiments with Sphere and Summation Cancellation, but this time the variables in the first tree in the decomposition are ordered randomly instead of representing the strongest bivariate dependences. The instances of the algorithms selected in these experiments are those that showed the best performance in the truncation experiments of the previous section. The results are presented in Tables 11 and 12.

In the Sphere function, the algorithms that use a random structure exhibit a better performance, since the number of product copulas that are fitted is greater. In this case, the estimated model resembles independence model used by UMDA, which indeed exhibits the best performance with the Sphere function. The opposite occurs with Summation Cancellation, where the use of a random structure in the first tree causes that important correlations for an efficient search are not represented, which deteriorates the performance of the algorithms in terms of the number of function evaluations. The main conclusion of this part is that it is necessary to make a careful selection of the structure of the pair-copula decomposition. The representation of the strongest dependences is important in order to construct more robust vine-based EDAs.

Table 11: Results of VEDA with a random selection of the structure of the first tree of the vines at each generation in Sphere with $X_i \in [-600, 600]$, $i = 1, \dots, 10$.

Algorithm	Success	Population	Evaluations	Best Evaluation
CVEDA _{BIC, random, g}	30/30	100	$4,523.3 \pm 100.6$	$6.9E - 07 \pm 1.8E - 07$
DVEDA _{BIC, random, g}	30/30	100	$4,526.6 \pm 114.2$	$6.6E - 07 \pm 1.6E - 07$

Table 12: Results of VEDA with a random selection of the structure of the first tree of the vines at each generation in Summation Cancellation with $X_i \in [-0, 16, 0, 16]$, $i = 1, \dots, 10$.

Algorithm	Success	Population	Evaluations	Best Evaluation
CVEDA _{AIC, random, g}	30/30	775	$110,360.0 \pm 2,020.9$	$1.0E + 05 \pm 1.1E - 07$
DVEDA _{AIC, random, g}	30/30	1500	$255,900.0 \pm 5,205.7$	$1.0E + 05 \pm 1.2E - 07$

5. RELATED WORK

For the sake of completeness, we present in this section a short review of representative EDAs based on copulas, with particular attention to EDAs based on copula factorizations because of their relevance to this paper.

The research on EDAs based on multivariate copulas has been focused on the use of multivariate elliptical copulas and Archimedean copulas. The algorithms described in [51, 3, 6] are based on the multivariate normal copula with differences in the estimation of the marginal distributions and the use of additional techniques such as variance scaling. An EDA based on the bivariate normal copula and normal marginal distributions is presented in [55], being an alternative formulation of EMNA. On the other hand, the algorithms presented in [54, 19] use exchangeable Archimedean copulas.

Several EDAs based on factorized copulas – such as empirical factorizations, nested Archimedean copulas and pair-copula constructions – have been studied. The EDA introduced in [44] constitutes an extension of the Mutual Information Maximization for Input Clustering (MIMIC) algorithm for continuous domains [34, 35] that uses bivariate copulas instead of bivariate normal distributions in the chain structure. Building from nested Archimedean copulas, an EDA that uses a representation of hierarchically nested Archimedean copulas based on Lévy subordinators is presented in [56]. Also, the use of bivariate empirical copulas and a multivariate extension of Archimedean copulas is investigated in [14].

The class of VEDAs studied in this paper is introduced in [50, 23] with two instances based on C-vines and D-vines, respectively. The algorithm presented in [45] also uses a D-vine model, but only normal copulas are fitted in the first two trees and conditional independence is assumed in the rest of the trees – i.e. the D-vine is always truncated at the second tree. Although it is stated in [45] that for practical purposes it is not necessary to build the complete D-vine, it was illustrated in Section 4.3.2. that the arbitrary selection of the number of trees in the vines compromises the convergence of the EDA. In [45], the selection of the structure of the D-vine is based on the minimization of the Kullback-Leibler divergence between the true unknown density function and the density function estimated using the truncated D-vine factorization.

The algorithm presented in [46] constitutes an extension to the continuous domain of the EDA based on discrete dependency trees described in [5]. This EDA employs a dependency tree along with bivariate copulas. The algorithm selects the copula that best fits a bivariate sample among six candidate copulas. The strategy followed to learn the tree structure is in the same spirit of [44] – i.e. to minimize the Kullback-Leibler divergence. This is achieved by finding the tree that results in the highest pairwise mutual information through a minimum spanning tree.

6. CONCLUSIONS

This paper presents a study of a class of EDAs called VEDAs. In particular, two algorithms of this class are investigated: CVEDA and DVEDA, which model the search distributions using C-vines and D-vines, respectively. The copula EDAs based on vines are more flexible than those based on the multivariate product and normal copulas, because the PCC models can describe a richer variety of dependence patterns. Our empirical investigation confirms the robustness of CVEDA and DVEDA in both strong and weak correlated problems.

We have found that building the complete structure of the vine is not always necessary. However, cutting the model at a tree selected arbitrarily could cause that important dependences are not represented. A more appropriate global strategy could be to combine setting a maximum number of trees with a model selection technique, such as the truncation method based on AIC or BIC. We also found that it is important to make a conscious selection of the pairwise dependences represented explicitly in the model.

Our findings show that both the statistical properties of the margins and the dependence structure play a crucial role in the success of optimization. The use of copulas and vines in EDAs represents a new way to deal with more flexible search distributions and different sources of complexity that arise in optimization.

As future research we consider to extend the class of VEDAs with regular vines. Our algorithms have been used in the optimization of test functions, such as the ones proposed in CEC-2005 benchmark [53]. In general, these functions display independence or linear correlations. In the future, we will seek problems with relevant dependences to the vine models studied in this work.

7. *APPENDICES

A EXPRESSIONS OF THE H AND H^{-1} FUNCTIONS OF VARIOUS BIVARIATE COPULAS

The pair-copulas used in this work are product, normal, Student's t , Clayton, rotated Clayton, Gumbel and rotated Gumbel. This appendix contains the definition of these copulas and the h and h^{-1} functions required to use this copulas in pair-copula constructions.

The Bivariate Product Copula

An immediate consequence of Sklar's theorem is that two random variables are independent if and only if their underlying copula is $C_I(u, v) = uv$. For this copula $h_I(x, v) = x$ and $h_I^{-1}(u, v) = u$.

The Bivariate Normal Copula

The distribution function of the bivariate normal copula is given by

$$C_N(u, v; \rho) = \Phi_\rho(\Phi^{-1}(u), \Phi^{-1}(v)),$$

where Φ_ρ is the bivariate normal distribution function with correlation parameter ρ and Φ^{-1} is the inverse of the standard univariate normal distribution function. For this copula the h and h^{-1} functions are

$$h_N(x, v; \rho) = \Phi\left(\frac{\Phi^{-1}(x) - \rho \Phi^{-1}(v)}{\sqrt{1 - \rho^2}}\right),$$

$$h_N^{-1}(u, v; \rho) = \Phi\left(\Phi^{-1}(u) \sqrt{1 - \rho^2} + \rho \Phi^{-1}(v)\right).$$

The derivation of these formulas are given in [1].

The Bivariate Student's t Copula

The distribution function of the bivariate Student's t copula is given by

$$C_t(u, v; \rho, \nu) = t_{\rho, \nu}(t_\nu^{-1}(u), t_\nu^{-1}(v)),$$

where $t_{\rho, \nu}$ is the distribution function of the bivariate Student's t distribution with correlation parameter ρ and ν degrees of freedom and t_ν^{-1} is the inverse of the univariate Student's t distribution function with ν degrees of freedom. For this copula the h and h^{-1} functions are

$$h_t(x, v; \rho, \nu) = t_{\nu+1} \left(\frac{t_\nu^{-1}(x) - \rho t_\nu^{-1}(v)}{\sqrt{\frac{(\nu + (t_\nu^{-1}(v))^2)(1-\rho^2)}{\nu+1}}} \right),$$

$$h_t^{-1}(u, v; \rho, \nu) = t_\nu \left(t_{\nu+1}^{-1}(u) \sqrt{\frac{(\nu + (t_\nu^{-1}(v))^2)(1-\rho^2)}{\nu+1}} + \rho t_\nu^{-1}(v) \right).$$

The derivation of these formulas are given in [1].

The Bivariate Clayton Copula

The distribution function of the bivariate Clayton copula is given by

$$C_C(u, v; \theta) = (u^{-\theta} + v^{-\theta} - 1)^{-1/\theta}, \quad (\text{A8})$$

where $\theta > 0$ is a parameter controlling the dependence. Perfect dependence is obtained when $\theta \rightarrow \infty$, while $\theta \rightarrow 0$ implies independence. For this copula the h and h^{-1} functions are

$$h_C(x, v; \theta) = v^{-\theta-1} (x^{-\theta} + v^{-\theta} - 1)^{-1-1/\theta},$$

$$h_C^{-1}(u, v; \theta) = \left((uv^{\theta+1})^{-\theta/(\theta+1)} + 1 - v^{-\theta} \right)^{-1/\theta}.$$

The derivation of these formulas are given in [1].

The Bivariate Rotated Clayton Copula

The bivariate Clayton copula, as defined in (A8), can only capture positive dependence. Following the transformation used in [12], we consider a 90 degrees rotated version of this copula. The distribution function of the bivariate rotated Clayton copula is obtained as

$$C_{RC}(u, v; \theta) = u - C_C(u, 1 - v; -\theta),$$

where $\theta < 0$ is a parameter controlling the dependence and C_C denotes the distribution function of the bivariate Clayton copula. For this copula the h and h^{-1} functions are

$$h_{RC}(x, v; \theta) = h_C(x, 1 - v; -\theta)$$

and

$$h_{RC}^{-1}(u, v; \theta) = h_C^{-1}(u, 1 - v; -\theta),$$

where h_C and h_C^{-1} denote the expressions of the h and h^{-1} functions for the bivariate Clayton copula.

The Bivariate Gumbel Copula

The distribution function of a bivariate Gumbel copula is given by

$$C_G(u, v; \theta) = \exp \left(- \left((-\log u)^\theta + (-\log v)^\theta \right)^{1/\theta} \right),$$

where $\theta \geq 1$ is a parameter controlling the dependence. Perfect dependence is obtained when $\theta \rightarrow \infty$, while $\theta = 1$ implies independence. The h function is

$$h_G(x, v; \theta) = C_G(x, v; \theta) \frac{1}{v} (-\log v)^{\theta-1} \left[(-\log x)^\theta + (-\log v)^\theta \right]^{1/\theta-1},$$

but h_G^{-1} cannot be written in closed form; therefore, we obtain it numerically using Brent's method [13]. The derivation of these formulas are given in [1].

The Bivariate Rotated Gumbel Copula

The bivariate Gumbel copula can only represent positive dependence. As for the bivariate Clayton copula and following the transformation used in [12], we also consider a 90 degrees rotated version of the bivariate Gumbel copula. The distribution function of the bivariate rotated Gumbel copula is defined as

$$C_{RG}(u, v; \theta) = u - C_G(u, 1 - v; -\theta),$$

where $\theta < -1$ is a parameter controlling the dependence and C_G denotes the distribution function of the bivariate Gumbel copula. For this copula the h and h^{-1} functions are

$$h_{RG}(x, v; \theta) = h_G(x, 1 - v; -\theta)$$

and

$$h_{RG}^{-1}(u, v; \theta) = h_G^{-1}(u, 1 - v; -\theta),$$

where h_G and h_G^{-1} denote the expressions of the h and h^{-1} functions for the bivariate Gumbel copula.

RECEIVED: OCTOBER, 2013.

REVISED: MAY, 2014.

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